# n de fr es cs



**OMX 390LVDT** 

# Description

- Power supply of LVDT sensor 1 / 3 / 5 Vac
- 3-/4-/5-/6-wire connection
- Data output Modbus TCP/IP
- Quick configuration by DIP switch
- PC configurable via USB port
- Galvanic isolation 2.5 kVAC
- Simple instalation to DIN rail

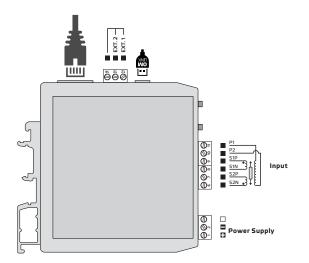
#### **Digital DIN rail mounted signal** conditioner INPUT FOR LVDT SENSORS IN 1 OUT 1 LVDT ModB Ø Ø 485 **))))** IP/TCP **(3**) Input Ø 1-Power

CISB CISB	Hi Lo	Status
		Device is running
	*	Device functionality is limited, powered via USB
	*	This device has a Delayed Start option
	•	Error: device is out of order
		Tare function is activated
	• •	Error: of input (> ±110% of range) or of sensor [ERR.1- 2]
	• •	Error: AO loop open [ERR.10]
	• •	Error: setting/calibration [ERR.34-36]
	* *	Serious error (Safe mode) [ERR.50]
	* *	Button function is blocked
	• •	Simulation mode is activated
		Legend
		<ol> <li>Connectors</li> <li>Control button</li> <li>RGB Status LED</li> </ol>

	M WARNING
HAZARD OF ELECTRICAL SHOCK - Disconnect all power and other supply lines before servicing equipment	EQUIPMENT OPERATION HAZARD - Do not use this product in safety critical system - Do not disassemble, repair or modify this product - Do not operate beyond the recommended operating environment
Failure to follow this instruction may result in death or serious injury.	Failure to follow these instructions may result in death, serious injury, or equipment damage.

Electrical equipment should be installed, operated, serviced, and maintained only by qualified personnel. No responsibility is assumed by ORBIT MERRET for any consequences arising out of the use of this device.

# 2 Connection

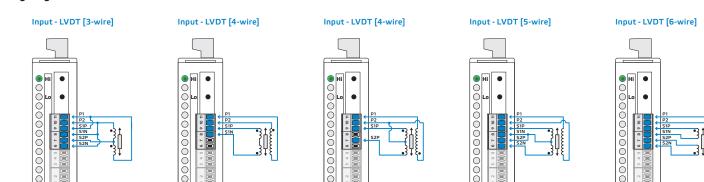


#### Note

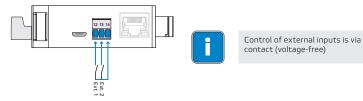
Contactors, high power electric motors, frequency drives and other power devices should not be in a close proximity of the meter. Input signal leads (measured value) should be seperated from all power lines and power devices. Even though the device has been designed and tested according to standards for industrial environment, we strongly advise to adhere to the above presented rules.

0,051,5 mm² 3016 AWG	8 0.32
Ø 3,5 mm Ø 0.14 in	C (∅)) 1,5 Nm 13.2 lb-in

#### Wiring diagram



#### Input - External inputs



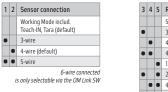
#### 3

**DIP** switch

For a quick set up you can use the DIP switch. Changing a configuration only takes effect after power off/on.

6 7 8 Data output

Modbus TCP/IP (defaulf)



**Device setting** 

3	4	5	Rate [measurements/s]
			50
•			300
	•		400
•	•		400 - FFT
		٦	1200
•		•	2400
	•		4800
•	•		7200 (default)

#### Analog input range setting, TEACH-IN

- 1. Enter the teach-IN mode by a short press of the Lo button LED HI 🍀 yellow and LED Lo 🔵 turquoise
- 2. Put the connected sensor in the position that shall have minimum output **RNG.MIN** (for example 0.02 mV)
- 3. Set the minimum output value by a long press (>2 s) of the Lo button LED Hi 🍀 yellow, LED Lo 🛑 purple
- 4. Put the connected sensor in the position that shall have maximum output **RNG.MAX**. (for example 20.01 mV)
- 5. Set the maximum output value by a long press (>2 s) of the Lo button LED HI 😤 yellow, LED Lo 🄍 green
- 6. Leave teach-IN mode by a short press of the Lo button and return to the standard working mode LED HI S green The teached measuring range is non volatile and retained even after power off/on

### Zero settings (Tare)

- 1. Enter the tare mode by a short press of the Hi button LED Hi 🏶 white and LED Lo 🗨 turquoise
- 2. Put the connected sensor in the position where the tare function shall be executed
- 3. Set the tare by a long press (>2s) of the Hi button LED Hi  $\bigotimes_{-}^{\infty}$  white, LED Lo  $\bigcirc_{-}$  green
- 4. Leave tare mode by a short press of the Hi button LED Hi lacksquare green, LED Lo igtarrow white
- The tare is always reset automatically when the device is switched off.

## Offset settings, Teach-In

- 1. Enter the Teach-in for Offset mode by a long press of the Hi button LED Hi 🏶 white and LED Lo 🍀 turquoise
- 2. Put the connected sensor in the position where the Offset function shall be executed
- 3. Set the Offset by a long press (>2s) of the Hi button LED Hi % white, LED Lo lacksquare green
- 4. Leave Offset mode by a short press of the  ${
  m Hi}$  button LED  ${
  m Hi}$  green

# Description of Modbus registers

The new device protocol supports reading and writing multiple registers at the same time. Each register is 2 bytes in size. Values of type float32 are stored in two registers (4 bytes).

You can find a detailed description of the protocol on our website Modbus Protocol Registry Application Sheet

https://www.orbitmerret.eu/cs/document-download?document\_id=13642



Setting of Analog input TEACH-IN is active only when DIP switches No. 1-2 are in the "O" position, i.o. Setting via OM Link



In order to avoid possible unintended changes to settings by accidentally pressing the **Hi** and **Lo** buttons, these buttons can be **disabled** by connecting **terminals No. 12** and **14** of external inputs EXT.1 (wire jumper).



A short press at any time during the calibration will end the calibration without saving.After one minute of inactivity, the calibration is terminated without saving and both LEDs return to the basic state.

# Inputs

Reset of Tare	CLEAR	>	CL.TAR. Tare resetting
Sampling rate	READ. S.	>	1         2.5         5         10         25         50         100         Measuring rate selection
Sensor power supply	POWER	>	1V-2.5k 1V-10k 3V-2.5k 3V-10k 5V-2.5k 5V-5k 5V-10k Selection of LVDT sensor power supply
Gain	GAIN	>	1 2 4 8 Selection of signal amplification from LVDT sensor
Sensor connection	CONNEC.	>	3-wire 5-wire 5-wire Selection of the LVDT sensor connection type
Offset, Teach-in	M.RANGE	>	YES       Offset setting (shift "0") in learning mode       T-IN.LO       Device measures the value of the Lo signal
Offset	T-IN.OF.	>	09999 Setting the offset value ("0") YES Lo signal connection confirmed
Setting of converted value	OFFSET	>	-999990999999 For the minimum of the selected input range
	RNG.MIN.	>	•9999920999999       For the maximum of the selected input range*       YES       Hi signal connection confirmed
Input setting Expert	RNG.MAX.	>	T-IN.LO T-IN.HI Setting the input range in the Teach-in mode
	TEACH-IN	>	MAN. LO MAN. HI Setting the input range in the Manual mode
Digital filters	MANUAL	>	OFF       AVERAG.       FL. AVG.       EXPON.       Filters for math. adjust. of the input signal       MAN. HI       Manual entry of Hi input signal for MAX
Filter constant	F.MODE	>	09999 Setting the constant for the filter 2.991 Entry of signal value (example: 2.991 V)
External input	F.CONST.	>	OFF     TARE     CL.TAR.     TAR-CL     CUM.SUM.     T-IN.OF.     HoLD     SAMPLE     HLD.MIN     HLD.MAX     HLD.PRM.     KEY.LCK.     Fce selection EXT. 1
	EXT.IN.1	>	OFF     TARE     CL.TAR.     TARCL     CUM.SUM.     T-IN.OF.     HoLD     SAMPLE     HLD.MIN     HLD.MAX     HLD.PRM.     KEYLCK.     Fce selection EXT. 2
	EXT.IN.2	>	

# **Function**

Mathematical function	INP. M.F.	>	OFF INPUT INR.FIL. INP.ABS. Input selection for the math function	POLYN.	Polynomial	$Ax^{5}+Bx^{4}+Cx^{3}+Dx^{2}+Ex+F$
	TYPE.M.F.	>	POLYN. IN. POL. LOGAR. EXPON. POWER SQ.ROOT	IN. POL.	Inv. polynomial	$\frac{A}{x^{5}} + \frac{B}{x^{4}} + \frac{C}{x^{3}} + \frac{D}{x^{2}} + \frac{E}{x} + F$
	CONST. A F	>	099 Setting constants for mathematical functions	LOGAR.	Logarithmic	$A \times \ln \left(\frac{Bx + C}{Dx + E}\right) + F$
Linearization table	INP. L.T.	>	OFF INPUT FILTER. Input selection for the linearization table	EXPON.	Exponential	$A \times e^{\left(\frac{Bx+C}{Dx+E}\right)} + F$
	N.OF.PTS.	>	5100 Number of points in the table	POWER	Power	$A \times (Bx + C)^{(Dx+E)} + F$
	VALUES	>	-999999999 Values of X/Y	SQ.ROOT	Square root	$A \times \sqrt{\frac{Bx + C}{Dx + E}} + F$

# Output

Modbus TCP/IP	DHCP	> YES NO	Selection of assigning IP addresses
	IP.ADR.	> 192.168.88.40	IP Address setting (IPv4)
	MASK	> 255.255.255.0	Subnet Mask setting
	GATE	> 192.168.88.1	Default Gateway setting
	PORT	> 1 <u>502</u> 65535	Port setting

# Service

Setting of password	PASSW.	> 09999 Password to connect the device to PC. If it is set to "0", access is not blocked
Delayed Start	DLY.STR.	> 099 Setting the time [sec] - when the measurement is not performed after powering the device on
Save user settings	SAV.SET.	> YES Saves the current device settings
Load user settings	LOA.SET.	> YES Loads the user settings into the device
Factory reset	FACT.ST.	> YES Loads the original factory settings, restores the initial settings (BLUE TEXTS)
Erase user calibration	CLR.CAL.	> YES Clears user calibration, restores factory calibrations (after user calibration by script via OM Link SW had been performed)
Key lock	KEY.LCK.	> ON OFF Disables the push button(s) on the front panel of the device
Error selection for signalling	SIG.ERR.	FRR 1         ERR 20         ERR 21          Errors that will be signalled on the selected output
Simulation of input signal	SIM.MIN.	> MIN > -999990999999 Setting of the start of the range for simulation
	SIM.MAX.	> MAX > -9999910099999 Setting of the end of the range for simulation
	STEP	> -9999919999999 Setting of increment/step value
	TIME	Setting the increment/step duration time [sec.]
	START	STOP Start of simulation
	STOP	START > YES     Stop of simulation
		Error messages

The USB connector is galvanically connected to the input! USB-to-USB Isolator must be used when input signal is connected to the device. DANGER OF COMPUTER DAMAGE

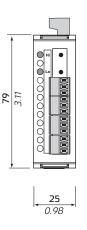
# Error messages

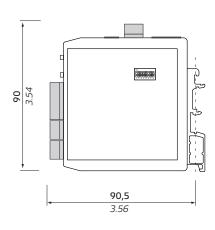
Error	Error description	Solution
ERR 1	Input range exceeded by ±10% or more.	Change input signal value or input setting (range).
ERR 2	AD converter overflow / underflow.	Change input signal value or input setting (range).
ERR 20	Math function error.	Change math function settings.
ERR 21	Linearization table error.	Change/complete the settings of the linearization table.
ERR 30	Powered only by USB, analog circuits inactive.	Connect power supply to the device (clamp 1,2).
ERR 34	User configuration could not be loaded from EEPROM. Default configuration automatically applied.	Repeat device configuration. If message is shown repeatedly, send the device for repair.
ERR 35	Factory calibration has been lost. Converter's accuracy is compromised up to ±5%	When this error occurs, send the device for re-calibration or upload factory calibration data.
ERR 36	User calibration could not be loaded from EEPROM. Factory calibration automatically applied.	Repeat the user calibration. If message is shown repeatedly, send the device for repair.
ERR 50	Serious device error - damaged EEPROM. The device operates in an emergency mode, i.e. settings cannot be changed. Measurement error can be up to 5%	Send the device for repair.

Errors ERR 34-50 are displayed permanently, until they are corrected.

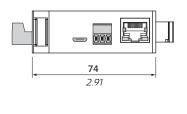


Side view





**Top view** 



mm inch

Installation to DIN rail of 35 mm width

# **Technical data**

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#### INPLIT No. of inputs Dual 24-bit $\Delta\Sigma$ ADC with PGA with demodulator Setting and wake-up signal generator The range is selectable either by DIP switch or by OM Link free SW from PC LVDT Sensor 1, 3 or 5 VAC with frequency 2.5, 5 or 10 kHz power supply Preamplifier gain 1, 2, 4 or 8 Connection 3-, 4-, 5- or 6-wire EXTERNAL INPUT No. of inputs 2, on contact Function OFF No function assigned OFF No function assigned TARE Activation of Tare CLTAR. Clear Taree (Clear Taree CLTAR. Clear Taree CLMS.UM. Control of Cumulative measurement HOLD Measurement paused SAMPLE Initiates a one-off measurement HLDMX Hold - Value of Minimum\* HLDMX Hold - Value of MAXImum\* HLDMX Hold - Value of MAXImum\* HLDAYE Hold - VAlue

	Sensor	1, 3 OF 5 VA	AC WITH TREQUENCY 2.5, 5 OF TU KHZ	Overload	10x (t < 30 ms), 2x
	power supply Preamplifier	1, 2, 4 or 8		Functions	Teach-in, tare, offset, min/max value, math. functions, delayed start, simulation
	gain Connection	3-, 4-, 5- 0	r 6-wire	Weighing functions	automatic zero tracking, automatic tare, setting of scale division (0.001100)
EXTE	RNAL INPUT			Digital filters	exponential / floating / arithmetic average, ouding
	f inputs	2, on contact		Math functions	polynomial / inverse polynomial / logarithm / exponential / power / root
Function		ARE Activation of Tare LTAR. Clear Taree RA:CL Activat. of Tare (+1.5) * clear Tare (>1.5) IN.OF. Activation of Tech-In for Offset UM.SUM. Control of Cumulative measurement OLD Measurement paused AMPLE Initiates a one-off measurement LD.MIN Hold - Value of Minimum* LD.MAX Hold - Value of MAX:MIN*	Linearization	linear interpolation in 100 points only via OM Link	
			OM Link	company communication interface for operation, setting and update of instruments. (microUSB)	
			Watch-dog	reset after 500 ms	
			SAMPLE	Calibration	at 25°C and 40 % r.h.
			HLD.MAX I	DATA OUTPUT	
			HLD.M-M HLD.AVG	o. of outputs	1
		KEY.LCK.		Туре	10/100BaseT
*The value is calculated from the period starting with the previous external input activation.				Protocol	Modbus TCP/IP (Slave)

INSTRUMENT SPECIFICATION

25 ppm/°C

< 580 µs

±0.1% of FS

1...100 measurements/s

TC

Accuracy

Rate

Ra Set

Latency

ofoutputs	1
pe	10/100BaseT
otocol	Modbus TCP/IP (Slave)
te	100 Mbit/s.
tting	DHCP IPv4 Address Subnet Mask Default Gateway Port

#### POWER SUPPLY

Power	1030 VDC/24 VAC, ±10 %, PF $\ge$ 0.4, I <sub>STP</sub> < 40 A/1 ms, isolated Fuse inside (T500mA)	
Consumption	< 3.4 W / 3.3 VA < 5.0 W / 4.9 VA (at 80 Ω load)	

### MECHANIC PROPERTIES

Material	PA66, incombustible UL 94 V-0, green
Dimensions	25 x 79 x 90.5 mm (w x h x d)
Installation	to DIN rail 35 mm wide

#### **OPERATING CONDITIONS**

Connection	connector terminal blocks, section < 1.5 mm <sup>2</sup>
Stabilization period	within 5 minutes after switch-on
Working temp.	-20°60°C
Storage temp.	-20°85°C
Working humidity	< 95 % r.h., non condensing
Protection	IP20
Construction	safety class I
El. safety	EN 61010-1, A2
Dielectric strength	2.5 kVAC for 1 min. between power supply and signal input 2.5 kVAC for 1 min. between signal input and outputs
Insulation resistance*	for pollution degree II, measurement cat. III power supply > 300 V (PI), 255 V (DI) Input/outputs > 300 V (PI)
EMC	EN 61326-1 (Industrial area)
RoHS	EN IEC 63000:2018
Seismic qualification	IEC/IEEE 60980-344 ed. 1.0:2020, par. 6, 9
Mechanical resistance	EN 60068-2-6 ed. 2:2008

\* PI - Primary insulation, DI - Double insulation

On our website <u>www.orbitmerret.eu</u> there are Application sheets available for the products under the "Download Support" tab, which provide a detailed description of the properties, functions and use of the device.





This product must be installed, connected and used in compliance with prevailing standards and/or installation regulations. As standards, specifications and designs develop from time to time, always ask for confirmation of the information given in this publication.







ORBIT MERRET, spol. s r.o. Vodňanská 675/30 198 00 Praha 9 Czech Republic

(C) +420 - 281 040 200 (@) info@orbitmerret.eu